KLJ Instruments

SQTR-3BB 1030/1090/UAT ADS-B Squitter Generator



Operators Manual

REVISION

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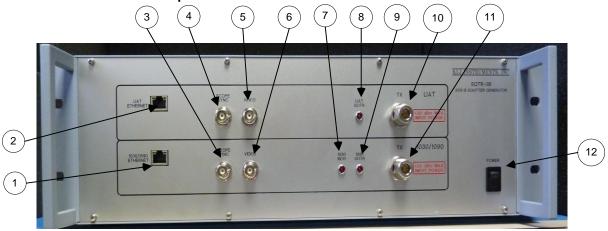
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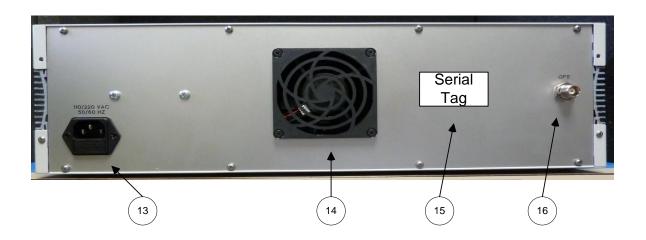
INTRODUCTION

1.1 Manual Description

The SQTR-3BB provides capability for generating ADS-B information (1090 MHz DF17 Squitters and Universal Access Transceiver (UAT) Messages) and 1030 MHz Mode S Interrogations. The purpose of this manual is to provide instructions for use of the SQTR-3BB.

1.2 Front and Rear Panel Description





| | SQTR-3BB Front and Rear Panel | | | | |
|----|-------------------------------|---|--|--|--|
| 1 | 1030/1090 ETHERNET | Ethernet connection for 1030/1090 Board | | | |
| 2 | UAT ETHERNET | Ethernet connection for UAT Board | | | |
| 3 | 1030/1090 SCOPE | Scope Sync output for each 1030 Interrogation or 1090 DF17 Squitters | | | |
| 4 | UAT SCOPE | Scope Sync output for each UAT Messages | | | |
| 5 | UAT VIDEO | Detected waveform of UAT Messages | | | |
| 6 | 1030/1090 VIDEO | Detected waveform of 1030 Interrogations or 1090 DF17 Squitters | | | |
| 7 | 1030 Interrogations | Flashes when transmitting 1030 Interrogations | | | |
| 8 | UAT Squitters | Flashes when transmitting UAT messages | | | |
| 9 | 1090 Squitters | Flashes when transmitting 1090 DF 17 squitters | | | |
| 10 | TX UAT | Output for UAT Messages | | | |
| 11 | TX 1030/1090 | Output for 1030 Interrogations or 1090 DF17 Squitters | | | |
| 12 | POWER | Power Switch | | | |
| 13 | INPUT POWER | Input for 110/220 VAC, 50/60 Hz | | | |
| 14 | FAN | | | | |
| 15 | SERIAL TAG | Shows SQTR-3BB information as well as Ethernet IP Address for UAT and 1030/1090 Board | | | |
| 16 | 3.3 VDC GPS ANTENNA | Connection for external GPS antenna | | | |

1.3 SQTR-3BB Function

The SQTR-3BB provides capability for generating the following signals:

- Simulation of forty-five (45) 1090 MHz squitters (10 moving and 35 stationary)
- Simulation of ten (10) UAT messages
- Simulation of 1030 MHz (Modes A, C, Mode A/Mode S All Call, Mode C/Mode S All Call, and Mode S)
 interrogations

The SQTR-3BB provides capability for generating scenarios for generating airborne targets transmitting data via ADS-B, either UAT messages or 1090 MHz DF-17/18/19 squitters.

The Waypoint data for each target can be set. The GPS position (latitude and longitude) of each target can be set to occur at a selected time. The SQTR-3BB will generate the moving GPS position between each waypoint. The scenario can be set to run for a specific time or the SQTR-3BB will continue to simulate a moving target after passing the last selected waypoint (unless a scenario run-time length is set in the System Setup screen.

Each target can be configured for specific event-points in which various actions can be programmed to occur. The actions that can be configured include:

- Event Squitter Data Event-driven squitters
- Surveillance Status
 - Special Position Identification (18 second)
 - o Permanent Emergency Alert (Alert)
 - Temporary Alert (Squawk)
- RF Level Offset from RF Level selected in System Setup screen (0 to +31 dB)
- Change status (change or unchanged) of Squitter types (DF 11 Acquisition, DF 17/18 Surface Position, DF17/18, DF17/18 Airborne Position, DF 17/18 Airborne Velocity, or DF17/18 Identification and Category) selected in 1090 Target Setup screen
- Encode data in Type 23 (Test), Type 28 (Aircraft Status), Type 29 (Target State), or Type 31 (Aircraft Operational Status) Squitters

1.4 Initial Setup

The SQTR-3BB consists of two transmit channels, one for either 1030 or 1090 MHz and the second for UAT messages. Each of the two transmitter channels is controlled using an Ethernet connection. The IP address for each board is shown on a tag mounted on the rear of the SQTR-3BB. The SQTR-3BB is shipped from the factory with the following IP addresses:

1030.1090 Board: 192.168.0.58
UAT Board: 192.168.0.59

You must configure the unit so that it can communicate on a network with your serial device. You can use the following procedures remotely or locally:

- Use a Telnet connection to configure the unit over the network.
- Use a terminal or terminal emulation program to access the serial port locally.

The series of prompts at which you enter configuration settings is called **Setup Mode**. The unit's configuration is stored in nonvolatile memory and is retained without power. You can change the configuration at any time. The unit performs a reset after the configuration has been changed and stored.

This chapter tells you how to access Setup Mode and the general procedure for accessing Setup Mode:

(Note – a summary of the method to access the SQTR-3B to change the IP address described below is as follows: Select '0' from the menu. Type in the new address in 'chunks' i.e. 192 <ENTER>, 168 <ENTER> 0 <ENTER> 243 <ENTER>. Then just press ENTER to keep all of the other settings until you get back to the menu. Then press 9 to Save and Exit)

Telnet Connection

To configure the unit over the network, establish a Telnet connection to port 9999.

To establish a Telnet connection:

1. From the Windows **Start** menu, click **Run** and type the following command, where x.x.x.x is the IP address, and **9999** is the unit's fixed network configuration port number:

Windows: telnet x.x.x.x 9999

UNIX: telnet x.x.x.x:9999

- 2. Click **OK**. The following information displays.
- 3. To enter Setup Mode, **press Enter within 5 seconds**. The configuration settings display, followed by the **Change Setup** menu.
- 4. Select an option on the menu by entering the number of the option in the **Your choice**? field and pressing **Enter**.
- 5. To enter a value for a parameter, type the value and press **Enter**, or to confirm a current value, just press **Enter**.
- 6. When you are finished, save the new configuration (option 9). The unit reboots.

Serial Port Connection

To configure the unit through a serial connection:

- 1. Connect a console terminal or PC running a terminal emulation program to your unit's serial port. The default serial port settings are **9600 baud**, **8 bits**, **no parity**, **1-stop bit**, **no-flow control**.
- 2. Reset the XPort Direct unit by cycling the unit's power (turning the power off and back on). Immediately upon resetting the device, enter three lowercase **x** characters (**xxx**).

Note: The easiest way to enter Setup Mode is to hold down the **x** key atthe terminal (or emulation) while resetting the unit. **You must do this within three seconds of resetting the** XPort Direct. At this point, the screen display is the same as when you use a Telnet connection. To continue, go to step 4 in *Telnet Connection*, above.

Exiting Setup Mode To exit setup mode:

You have two options:

- To save all changes and reboot the device, select option **9 Save and exit** from the **Change Setup** menu. All values are stored in nonvolatile memory.
- To exit the configuration mode without saving any changes or rebooting. Select option 8 Exit without save from the Change Setup menu.

The SQTR-3BB can be controlled using the graphical user interface (GUI) that is supplied with the unit or by the use of a terminal emulation program. KLJ recommends the use of a terminal emulation program called Tera Term Pro Web (instructions in this manual are written around Tera Term Version 3.1.3) which is a freeware program that can be downloaded from www.ayera.com/teraterm. After downloading the Tera Term program to your computer,

connect to the SQTR-3BB via your local Ethernet network or directly from your computer to the SQTR-3BB via a CAT 5E X-Over patch cable. If using the X-over patch cable, your computer IP Address must be configured to "talk" to the SQTR-3BB (suggest address of 192.168.0.40 for your computer) using START/CONTROL PANEL/NETWORK CONNECTIONS/LOCAL AREA CONNECTIONS/INTERNET PROTOCOL (TCP/IP). If you are using the Tera Term Web 3.1 program, FILE/NEW CONNECTION. Select TCP/IP and set Host to 192.168.0.58. Select OTHER and set TCP Port # to 10001. Press OK. You should see 192.168.0.58 VT if TeraTerm has connected to the SQTR-3BB. Select SETUP/TERMINAL and check the box next to LOCAL ECHO. To test the connection, type RFR?. The Tera Term program will show the current version of the RF board software loaded in the SQTR, i.e. SQTR 3(DA2): 0,9; Date 2/24/09. Some types of firewall programs can block the return of data from the SQTR-3BB. You may need to configure your firewall to accept the SQTR-3BB data.

1.5 Graphical User Interface (GUI) Program

The SQTR-3B is supplied with a distribution disk that contains the GUI file that allows the test set operator to configure the SQTR-3B for operation. Insert the disk supplied with the SQTR-3B into test computer drive. Copy the information on the disk to a folder on the test computer. After copying the files to the test computer, use computer Explorer program to view the files loaded onto the test computer. Click on Setup.Exe and follow the prompts for installation of the GUI. After installation of the GUI program, you can click on Client.Exe to start the SQTR-3B GUI.

The GUI allows the test set operator to configure the SQTR-3B for transmitting 1030 Interrogations, 1090 MHz ADS-B Squitters or UAT ADS-B Messages.

1.6 Example of Setup for typical 1090 MHz ADS-B Squitter Scenario

The SQTR-3B provides the capability for generation Mode S ADS-B Squitters, UAT Messages (Squitters), and Mode S Uplink Messages. Each of these functions has a similar operation in the SQTR-3B. The following is an example for setup of Mode S ADS-B Squitters.



Connect control computer to SQTR-3B 1030/1090 UAT connector. The computer can be connected to the SQTR-3B through a router or directly from computer to SQTR-3B using a crossover cable. Start SQTR-3B GUI program. The System Setup screen will appear. Enter the address of the 1030/1090 Ethernet port (marked on tag on back of SQTR-3B) in the IP Address field and Port 10001 n the Port Number field. Press the Connect 1030/1090



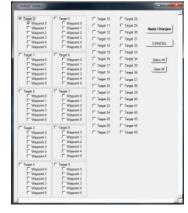
button and the green light indicating a valid connection should appear within ~30 seconds. Using the appropriate 1090 MHz fields and buttons on the right side of the screen, configure the SQTR-3B values (i.e. 1090 GPS coupled ON/OFF (leave OFF for now), Mode (leave at 0 for now), RF level (set to desired value), and Set Scenario Run Time Length (do not change for now).

Press the Configure the SQTR-3B button. The System Configuration screen will appear. Press the 1090 MHz ADS-B Button and the Target Setup for 1090 MHz screen will appear. The test set operator must setup a Scenario

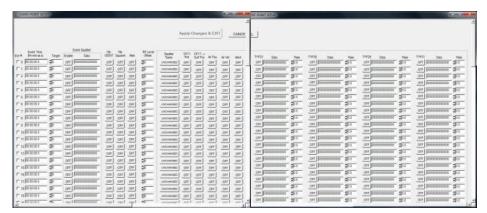
that specifies the number of targets and the information that will be transmitted by each target.



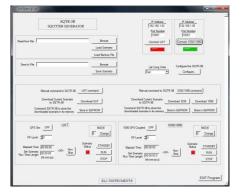
We will create a single 1090 MHz target that is stationary. The information to be transmitted in a 1090 MHz squitter is setup for each target. Use the Target # screen to enter a target number (i.e. Target # 0). Enter the information to be transmitted in Target # 0 (i.e. Mode S Address, RF Level Offset from value set in the System Setup Screen, Flight ID, etc.). The Waypoint field is used to make the target move if desired. To make the target move, calculate the latitude and longitude and the time for up to six waypoints. For



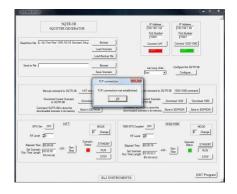
now, set waypoint 0 to latitude and longitude location of test set and leave the time fields set to zero. Additional parameters for each target can be selected. Set altitude to 2000 ft., and Vertical Status to Airborne. Press DF11 ACQ and Airborne Position buttons so that ON is displayed. Press the Enable Targets button and the Target Enable screen will appear. Select Target 0 and Waypoint 0 and press the Apply Changes button. This will return you to the Target Setup for 1090 MHz screen.



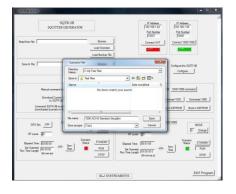
Press the Event Point Setup screen and the Event-Point Setup screen will appear. The Event-Point Setup screen will appear. The Event-Point Setup screen allows you to program various events to occur during a scenario. For now, do not program any events. Press the Cancel button and return to the Target Setup screen. If target information is completed for this scenario, press Exit (twice) and return to the System Setup Screen.







After configuration is completed, press the Download 1090 button. The GUI will display a Scenario Download screen to indicate that the scenario is being downloaded into the SQTR-3B. After completion of the download, press RUN to start the scenario causing the RUN button to turn green and the 1090 SQTR light should begin to flash. The SQTR-3B will continue to transmit ADS-B squitters at the standard rate for the type of squitter that was selected (you cannot change the rate) until the STOP button is pressed. The STOP button should always be pressed before a new configuration is programmed. If you do not press STOP and you press the Configure the SQTR-3B button, you will see a TCP connection error screen.



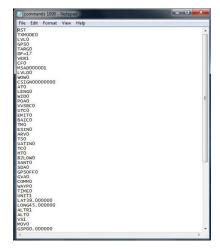




A scenario that has been loaded into the SQTR-3B can be saved and recalled for later use. To Save a scenario, press the Browse button in the Save to File section of the System Setup screen. A pop-up screen will allow you to name and save a scenario in a selected location. The scenario file will be saved as a binary (*.bin) file with a name selected by the test set operator (Note: the binary file cannot be changed using a text editor). To recall a saved scenario, press the Browse button in the Read from File section on the left side of the System Setup screen, locate

the saved file, highlight the file and press Select. After returning to the System Setup screen, press the Load Scenario button and then press the Download 1090 button. The saved scenario will be loaded into the SQTR-3B. After loading, press the RUN button and the scenario will begin to run.

A scenario for 1090 Squitters can also be created using commands described in Appendix A. A scenario can be created using a text editor such as Notepad (Note: do not use programs such as Microsoft Word as these types of programs insert additional hidden characters). A text file can be loaded into the SQTR-3B using a program like Tera Term as described in Section 1.4 of this manual (use send file operation of Tera Term). The SQTR-3B GUI can be used to create a sample text file for viewing of the commands described in Appendix A. The sample text file for 1090 squitters is created after a scenario is created using the GUI, downloading the scenario into the SQTR-3B, and pressing the RUN button. After the RUN button is pressed, use your computer Explorer program to view the folder that contains the GUI program and look for a file called "commands 1090". The commands 1090 file can be opened using a text editor like Notepad. After you open the commands 1090 file, you can see the commands that were sent by the GUI file to the SQTR-3B to run the scenario. For future reference, the commands 1090 file should be saved with a new name, as the file will be over-ridden each time a new scenario is downloaded to the SQTR-3B by the GUI.



1.7 GPS Antenna Setup

The SQTR-3B is supplied with a GPS antenna and 50 ft. of cable. A suitable cable may be used in place of the cable supplied with the SQTR-3B.

1.8 User Control – General Description

The SQTR-3BB can be controlled using a graphical user interface that allows limited control of the SQTR-3BB functions or through the use of manual user commands that allows control of all test set functions. The manual user commands can be sent to the SQTR-3BB using the Tera Term Web program.

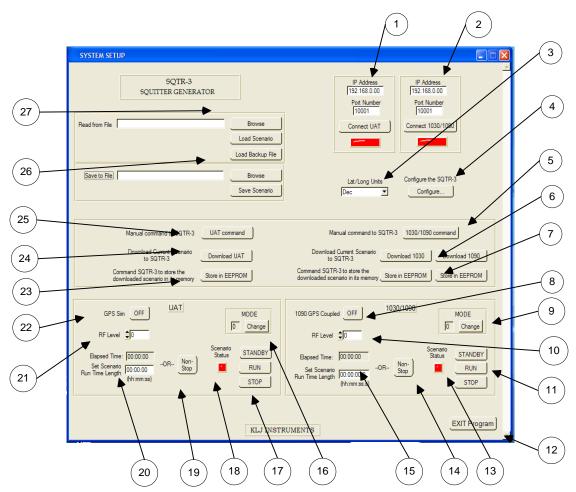
1.8.1 Graphical User Interface (GUI)

The graphical user interface (GUI) is shipped with the SQTR-3BB on a CD-ROM. To install the GUI on your computer, insert the CD-ROM into your CD/DVD drive. Using your Windows Explorer program, view the files contained on the CD-ROM. Select SETUP using your computer mouse. The SQTR-3BB will install the GUI on your computer (Note: Press OK if you get a message asking you to insert Disk 2, select OK). The GUI can be started using the CLIENT.EXE file.

The SQTR-3BB GUI is launched by selecting CLIENT.EXE in the directory where the GUI is installed (unless changed during installation, the directory will be C:\KLJ\SQTR3GEN). The following screen will be shown:



1.8.1.1 System Setup



SYSTEM SETUP Screen

System Setup Screen UAT - Used to connect GUI control to UAT Board. The computer must be connected to the UAT Ethernet connector. The UAT indicator light will turn green if connection is successful. 1030/1090 - Used to connect GUI control to 1030/1090 Board. The computer must be connected to the 1030/1090 Ethernet connector. Press 1030/1090 button and the screens shown in Figures 1 and 2 will pop-up. The UAT indicator light will turn green if connection is successful. 3 Lat/Long Units - Used to select Decimal or Degrees/Minutes/Seconds for display of GPS coordinates SQTR-3BB Configure - Used to configure the output of the SQTR-3BB. Press the Configure button and the screen shown in Figure 1 will pop-up. Select function to be configured. Depending on selection, the 1090 MHz ADS-B (see Figure 7), UAT ADS-B (Figure 10) or, 1030 MHz interrogations. 1030/1090 Manual Commands - Used to send user-defined commands to SQTR-3BB that do not have a control on a GUI screen (see Appendix A for list of commands). Press 1030/1090 button and Figure 2 will pop-up. Download 1030 or Download 1090 - Used to download the configuration or scenario for 1030 Interrogations or 1090 ADS-B from the control computer to the SQTR-3BB (a screen will pop-up indicating that the configuration is being downloaded to the SQTR-3BB). The

SQTR-3BB 1030/1090 Board can transmit 1030 Interrogations or 1090 ADS-B - not both at

the same time.

- 7 Store EEPROM Used to store in EEPROM the 1030 or 1090 configuration currently downloaded in the SQTR-3BB. Press the Store in EEPROM and a warning button (Figure 4) will pop-up with the stating that storing the information will take approximately 3.5 minutes. Press the "Yes, Continue" or "No, Cancel" button.
- 8 1090 GPS Coupled Used to set the time applicability of the 1090 position messages. GPS Coupled On means that the latitude and longitude of the targets are set exactly to the 0.2 second UTC epoch to which the position data is extrapolated. GPS Coupled Off means that the latitude and longitude are extrapolated to the time of message transmission.
- 1030/1090 Mode Used to select the SQTR-3B Start-Up Mode for 1030 and 1090. Press the Mode button and the SQTR Generator Mode 1030/1090 screen shown in Figure 3 will pop-up. Mode 0 is the default mode where the user must configure the SQTR-3B 1030 and 1090 functions. For Mode 1, the SQTR-3B at power-on will load the 1090 configuration stored in EEPROM and wait for the user to press the 1030/1090 Run button (item 11) to begin transmitting 1090 ADS-B (GUI must be re-connected to SQTR-3B. For Mode 2, the SQTR-3B at power-on will load the 1090 configuration stored in EEPROM and run the scenario until the time specified in the Set Scenario Run Time Length (item 16). For Mode 3, the SQTR-3B at power-on will load the 1090 configuration stored in EEPROM and run the scenario until the time specified in the Set Scenario Run Time Length (item 16) and then keep repeating the scenario. For Mode 4, the SQTR-3B at power-on will load the 1030 configuration stored in EEPROM and wait for the user to press the Run button (item 11) to begin transmitting 1090 ADS-B (GUI must be re-connected to SQTR-3B. For Mode 5, the SQTR-3B at power-on will load the 1030 configuration stored in EEPROM and continuously run the scenario. If the SQTR-3B has been sent a Mode 1, 2, 3, or 4, a Mode 0 must be sent to the SQTR-3B in order to return to normal operation where a new scenario can be configured and loaded.
- 10 RF Level Used to set the RF level of the 1030 and 1090 transmissions from +13 to -91 dBm
- 11 Standby/Run/Stop Used to control scenario Run starts scenario, Standby pauses scenario (hit Run to continue), and Stop (hit Run to re-start scenario)
- 12 Exit Program Used to exit and close GUI
- Scenario Status Indicates if 1030 or 1090 scenario is running (green), in standby (yellow) or stopped (red)
- Non-Stop Used to set scenario as configured with Waypoint settings to continuously run versus using Scenario Run Time Length (item 15)
- 15 Set Scenario Run Time Length and Scenario Elapsed Time Used to show scenario run and stop times as configured with Waypoint settings and the elapsed time for the 1030 or 1090 scenario.
- UAT Mode Used to select the SQTR-3B Start-Up Mode for UAT. Press the Mode button and the SQTR Generator Mode 1030/1090 screen shown in Figure 6 will pop-up. Mode 0 is the default mode where the user must configure the SQTR-3B UAT function. For Mode 1, the SQTR-3B at power-on will load the UAT configuration stored in EEPROM and wait for the user to press the UAT Run button (item 18) to begin transmitting 1090 ADS-B (GUI must be re-connected to SQTR-3B. For Mode 2, the SQTR-3B at power-on will load the UAT configuration stored in EEPROM and run the scenario until the time specified in the Set Scenario Run Time Length (item 21). For Mode 3, the SQTR-3B at power-on will load the UAT configuration stored in EEPROM and run the scenario until the time specified in the Set Scenario Run Time Length (item 21) and then keep repeating the scenario. If the SQTR-3B has been sent a Mode 1, 2, or 3, a Mode 0 command must be sent to the SQTR-3B in order to return to normal operation where a new scenario can be configured and loaded.
- 17 Standby/Run/Stop Used to control scenario Run starts scenario, Standby pauses scenario (hit Run to continue), and Stop (hit Run to re-start scenario)
- 18 Scenario Status Indicates if UAT scenario is running (green), in standby (yellow) or stopped (red)
- Non-Stop Used to set scenario as configured with Waypoint settings to continuously run versus using Scenario Run Time Length (item 20)
- 20 Set Scenario Run Time Length and Scenario Elapsed Time Used to show set scenario run time and the elapsed time for the UAT scenario.
- 21 RF Level Used to set the RF level of the UAT transmissions from 0 to -101 dBm

- 22 GPS Simulator Used to internally generate 1 PPS timing signal if external GPS signal not available for SQTR-3B
- 23 Store EEPROM Used to store in EEPROM the UAT configuration currently downloaded in the SQTR-3B. Press the Store in EEPROM and a warning button (Figure 5) will pop-up with the stating that storing the information will take approximately 3.5 minutes. Press the "Yes, Continue" or "No, Cancel" button.
- Download UAT Used to download the configuration or scenario for UAT ADS-B from the control computer to the SQTR-3B (a screen will pop-up indicating that the configuration is being downloaded to the SQTR-3B).
- 25 1030/1090 Manual Commands Used to send user-defined commands to SQTR-3BB that do not have a control on a GUI screen (see Appendix A for list of commands). Press 1030/1090 button and Figure 2 will pop-up.
- Save to File Used to store the current configuration as set by GUI currently downloaded into the SQTR-3B. UAT/1090 or UAT/1030 is saved in a file on the control computer. Use the Browse button to select the location for the file. Type a name for the file to be saved and then press the Save Scenario button to store the file. If you are going to replace a file or use the name of an existing file, use the Browse button to locate the file and press save. A message will pop-up asking if the file is going to be replaced press Yes, and then press the Save Scenario button to store the file.
- 27 Read from File Used to load a configuration file that was previously stored on the control computer. Use the Browse button to locate the file. Select the file to be loaded. Press the Load Scenario button to load the file. Download the file selected into the SQTR-3B using the appropriate Download buttons (items 7 and 26) the control computer must be connected to the correct Ethernet port for downloading.



Figure 1

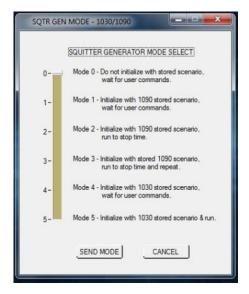


Figure 3

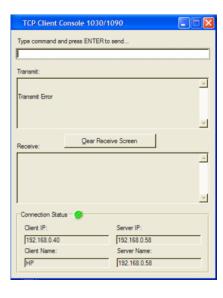


Figure 2

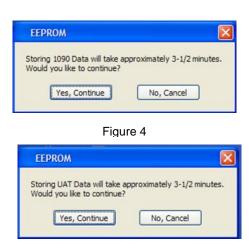


Figure 5

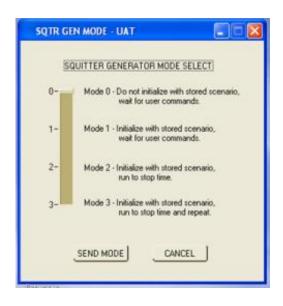


Figure 6

1.8.1.2 Target Setup for 1090 MHz Squitters

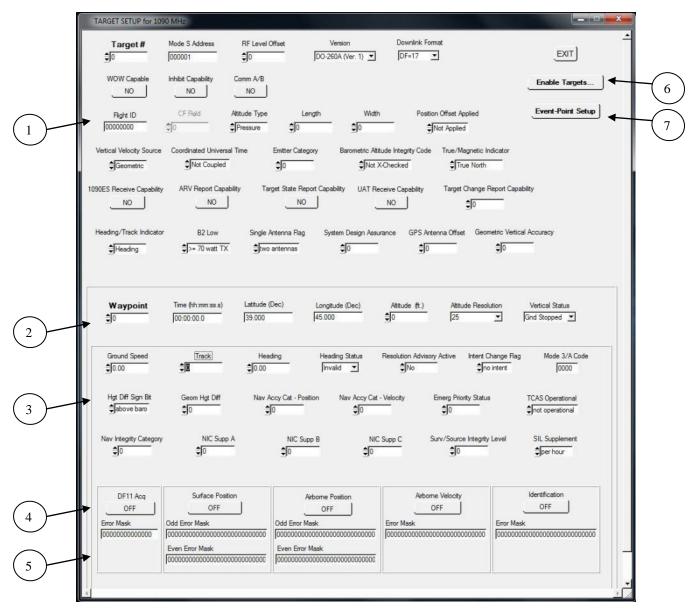
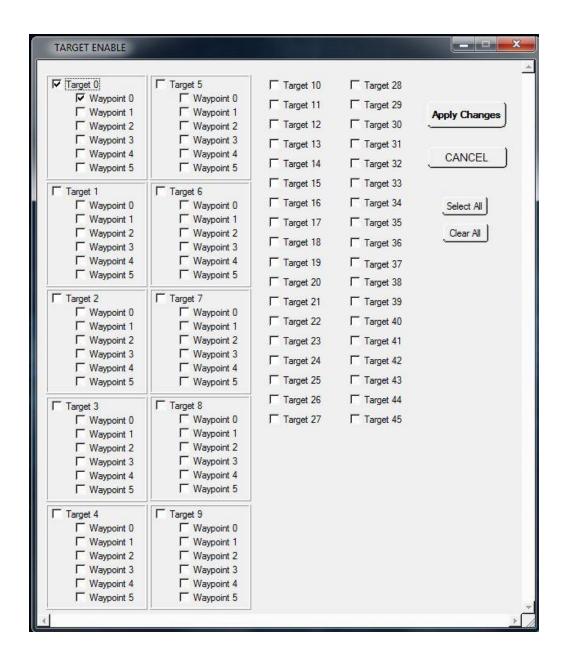


Figure 7

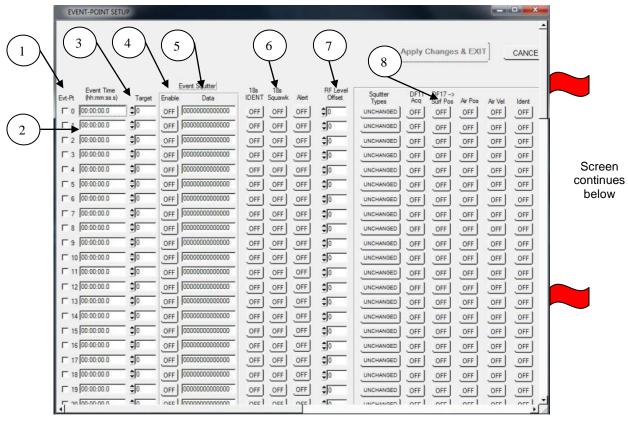
TARGET SETUP for 1090 MHz Screen

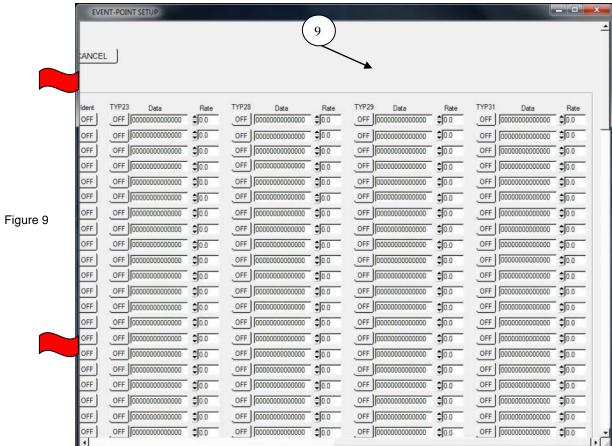
| | Target Setup Screen for 1090 MHz ADS-B Squitters (Figure 7) | | | | |
|---|---|--|--|--|--|
| 1 | Target Setup | Used to setup Target parameters | | | |
| 2 | Waypoint Setup | Used to setup Waypoint parameters for each Target | | | |
| 3 | Target Data Setup | Used to setup parameters for data in each target | | | |
| 4 | Squitter Activation Buttons | Used to activate squitter types | | | |
| 5 | Error Mask | Used to XORed squitter data with information contained in mask | | | |
| 6 | Enable Targets | Used to access TARGET ENABLE setup screen (Figure 8) | | | |
| 7 | Event-Point Setup | Used to access EVENT POINT setup screen (Figure 9) | | | |
| 8 | Exit | | | | |



A target and at least one waypoint must be selected or enabled for each Target in the Target Setup Screen (Figure 7)

| | Event Point Setup Screen (Figure 9 – next page) | | | | |
|---|---|--|--|--|--|
| 1 | Event Point Select | Used to enable an event point | | | |
| 2 | Event Time | Used to set time for event point | | | |
| 3 | Target # | Used to set Target # for this event | | | |
| 4 | Event Driven Enable | Used to enable an event squitter | | | |
| 5 | Event Squitter Data | Used to configure data contained in event squitter | | | |
| 6 | Surveillance Status | Used to set Surveillance Status bits in this event | | | |
| 7 | RF Level Offset | Used to set RF Level Offset from RF Level set in System Setup screen | | | |
| 8 | Change Squitter | Used to enable specific squitter types for this event | | | |
| 9 | Event Squitters | Used to enable and to configure data contained in Squitter Types 23, 28, | | | |
| | | 29, and 31 and to set squitter rate | | | |





1.8.1.3 Target Setup for UAT Messages

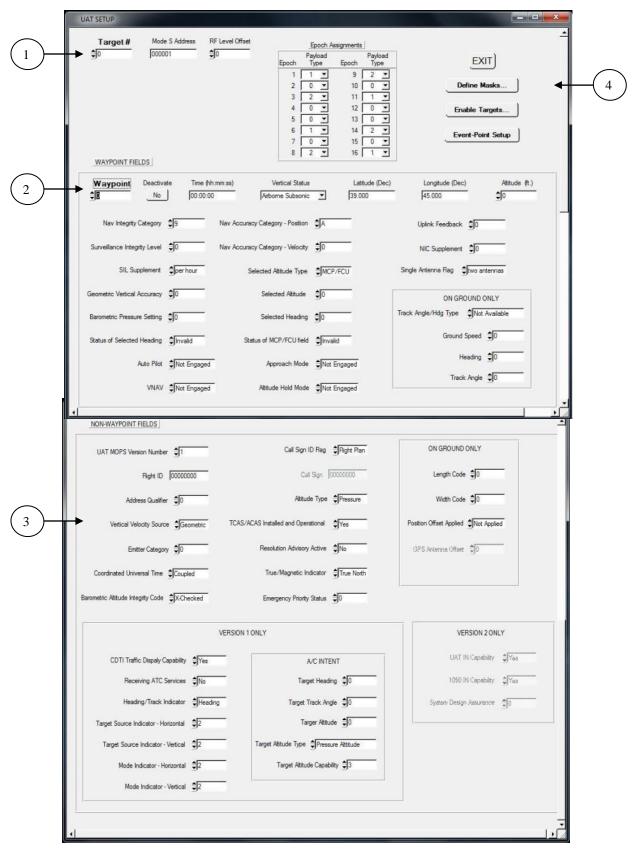


Figure 10

| | UAT Message Setup Screen (Figure 10) | | | |
|---|--------------------------------------|---|--|--|
| 1 | Target Setup | Used to configure Target parameters | | |
| 2 | Waypoint Fields Setup | Used to configure Waypoint parameters for each Target | | |
| 3 | Non-Waypoint Fields Setup | Used to configure data contained in Payload Fields | | |
| 4 | Define Masks | Used to access MASK SETUP screen (Figure 11) | | |
| 5 | Enable Targets | Used to access TARGET ENABLE setup screen (Figure 12) | | |
| 6 | Event-Point Setup | Used to access EVENT Point setup screen (Figure 13) | | |

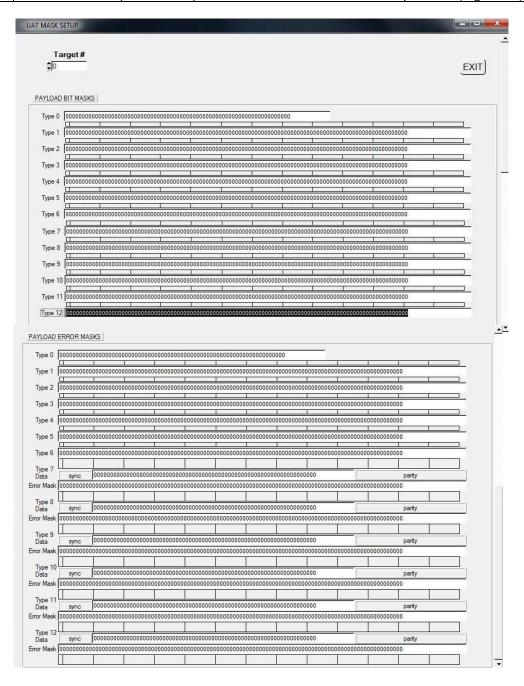
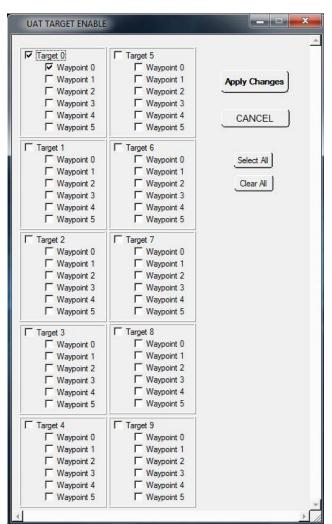


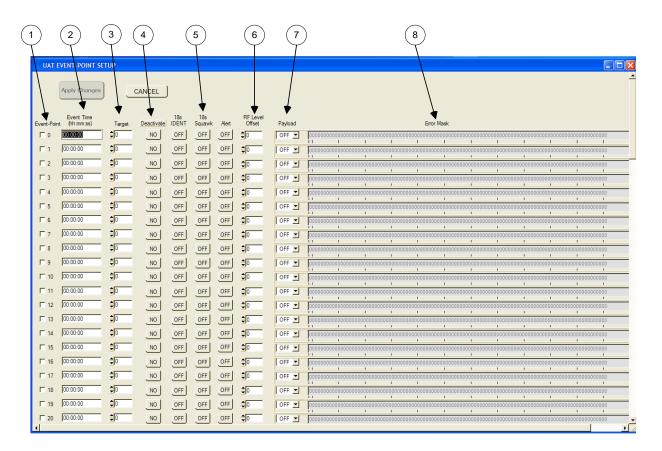
Figure 11

The UAT Mask Setup is used to enter data for each Payload Type and to enter a Payload Errors for each Payload Type. The data contained in the Error Mask will be XORed with the data in the Payload Bit Mask.



The UAT Target Enable screen is used to activate the target and waypoint that were setup on the UAT Setup screen. You must have a minimum of one target and one waypoint selected in order to generate a UAT target. After activation of the target and waypoint, press the Apply Changes button. You will be returned to the UAT Setup screen.

Figure 12

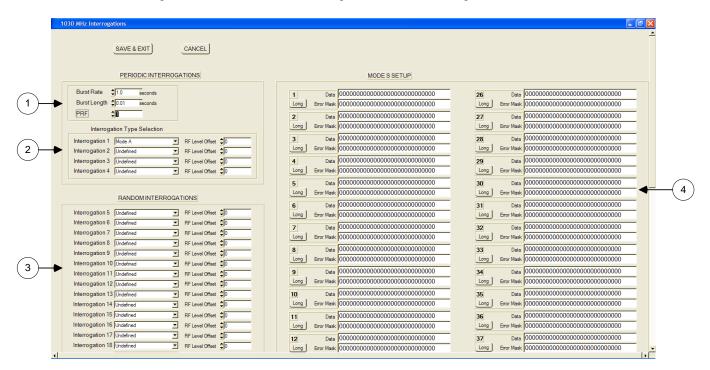


UAT EVENT POINT SETUP Figure 13

| | UAT Event Point Setup Screen | | | | |
|---|------------------------------|--|--|--|--|
| 1 | Event Point Select | Used to enable an event point | | | |
| 2 | Event Time | Used to set time for event point | | | |
| 3 | Target # | Used to set Target # for this event | | | |
| 4 | Deactivate | Used to deactivate an event point | | | |
| 5 | Surveillance Status | Used to set Surveillance Status bits in this event | | | |
| 6 | RF Level Offset | Used to set RF Level Offset from RF Level set in System Setup screen | | | |
| 7 | Payload | Used to select Payload Type for this event | | | |
| 8 | Payload Error | Used to XORed message data with information contained in mask | | | |

1.8.1.4 1030 MHz Interrogations

The 1030 MHz Interrogations screen is used to configure the 1030 Interrogations.



1030 MHz INTERROGATIONS Figure 14

| 1 | Periodic Interrogations | Setup | Used to set Burst Rate, Burst Length, and PRF of interrogations |
|---|-------------------------|-------|--|
| 2 | Periodic Interrogations | Туре | Used to set Interrogation Type and RF Level Offset from value set in System Setup Screen for each Periodic Interrogation |
| 3 | Random Interrogations | | Used to set Interrogation Type and RF Level Offset from value set in System Setup Screen for each Random Interrogation |
| 3 | Mode S Setup | | Used to set Mode S type (Short or Long), Data, and Error Mask for each of 50 interrogations |

1.8.2 Manual Commands

A list of manual commands for the SQTR-3B is contained in Appendix A of this manual. Scenarios can be created for each of the three functions using MS Notepad. After creating the scenario file, it can be downloaded to the SQTR-3B using Tera Term Pro Web (see Section 1.3). Each time that a scenario is configured and downloaded from the GUI to the SQTR-3B (1030 MHz Interrogation, 1090 Squitters, or UAT messages), the SQTR-3B generates three files in the directory containing the SQTR-3B program. The three files (commands 1030, commands 1090, or commands UAT) can be used by a new user of the SQTR-3B to view an example of the structure of the commands used to generate a scenario. This is useful for learning how to manually program the SQTR-3B.

1090/1030 SYSTEM COMMANDS

| Command | Format | Definition |
|---------|---|--|
| DLD | | Download the |
| | | microprocessor code |
| PGM | PGM – Programs the FPGA directly from the downloaded file | Download RF Board FPGA code |
| | PGM0 – store the downloaded file in the | |
| | onboard EEPROM for FPGA1 | |
| | PGM1 – Programs the FPGAs with the images contained in the onboard EEPROM PGM2 – store the downloaded file in the | |
| | onboard EEPROM for FPGA2 | |
| RST | | Reset the RF Board to its power-up state |
| TXF | TXF <float>, 952 – 1223 MHz</float> | Set the Transmit synthesizer frequency |
| BTR? | Return example: SQTR3 Boot Rev: 0.1; Date: 03/28/2008 | Request the BOOT code revision string. |
| GAR? | Return example: FPGA Rev Number: 65 | Request the FPGA1 revision string |
| RFR? | Return example: SQTR Gen Rev: 0.01; Date: 10/12/07 | Request the RF board revision string |
| SBY | , | Pauses the scenario |
| RUN | | Starts the scenario |
| STOP | | Stop the scenario |
| STOP | STOP <long></long> | Set the stop time for the scenario. LSB is 100ms. Setting the stop time to the maximum value (2147483647) essentially makes the scenario infinite. |
| | | Range: 0 to 2147483647 Resolution: 100ms |
| LVL | LVLd | Set the RF Level. |
| | | Range: 13 to –111dBm Resolution: 1dBm |
| SAVE | | Save the scenario to EEPROM |

| MODE | MODEd | Set the operating mode of the SQTR1. |
|-------|---|---|
| | | 0 = do not initialize with stored scenario, wait for user commands 1 = initialize with the stored scenario, wait for user commands 2 = initialize with the stored scenario, run to stop time 3 = initialize with the stored scenario, run to stop time and repeat |
| RAW? | return example: | Return the average raw temperature reading. |
| TMP? | return example: | Return the computed temperature (using the average raw temperature reading, calibrated slope and calibrated offset). |
| ТМРО | TMPO <float></float> | Set the offset for the temperature sensor transfer function. |
| TMPO? | return example: | Return the offset for the temperature sensor transfer function. |
| TMPS | TMPS <float></float> | Set the slope for the temperature sensor transfer function. |
| TMPS? | return example: | Return the slope for the temperature sensor transfer function. |
| CATT | CATT <coarse attenuation="" cal="" table=""></coarse> | Download the coarse attenuation calibration table. The CATT table is a two dimensional table (RF level vs. attenuator) containing values to be written to the 4 digital attenuators and an index into the FATT tables used to set the pin diode attenuator for each RF level setting from 13 to -111. |

| FATT | FATTd <fine attenuation="" cal="" table=""></fine> | Download the fine |
|------|---|--|
| | a simo attoridation dal tubios | attenuation tables. The |
| | FATT0 – download the FATT table for the | FATT tables are two |
| | UAT frequency of 978 MHz | dimensional tables (index |
| | | from the CATT table vs. |
| | FATT1 - download the FATT table for the | temperature) containing |
| | ground station frequency of 1030 MHz | values to be added to the |
| | | value obtained from the |
| | FATT2 - download the FATT table for the | BATT table and written to |
| | squitter frequency of 1090 MHz | the pin-diode to achieve the |
| | | "tweak" required to achieve |
| | | the requested RF level |
| | | once the four digital |
| | | attenuators are set to get |
| BATT | BATTd <frequency attenuation="" band="" cal<="" td=""><td>as close to it as possible Download the frequency</td></frequency> | as close to it as possible Download the frequency |
| DATI | table> | band attenuation tables. |
| | | The BATT tables are two |
| | BATT0 – download the BATT table for the | dimensional tables (index |
| | UAT frequency of 978 MHz | from the CATT table vs. |
| | | frequency offset band) |
| | BATT1 - download the BATT table for the | containing values to be |
| | ground station frequency of 1030 MHz | added to the value obtained |
| | | from the FATT table and |
| | BATT2 - download the BATT table for the | written to the pin-diode to |
| | squitter frequency of 1090 MHz | achieve the "tweak" |
| | | required to achieve the |
| | | requested RF level once |
| | | the four digital attenuators |
| | | are set to get as close to it as possible |
| CW | CW <channel><on off=""></on></channel> | Turn CW mode on or off on |
| | | each of the three channels. |
| | CW10 – turn CW OFF on channel 1 | |
| | CW11 – turn CW ON on channel 1 | |
| | CW20 – turn CW OFF on channel 1 | |
| | CW21 – turn CW ON on channel 1 | |
| | CW30 – turn CW OFF on channel 1 | |
| | CW31 – turn CW ON on channel 1 | T 011 |
| CAL | CAL <on off=""></on> | Turn CAL mode off and on. |
| | CAL0 – turn CAL mode OFF | |
| | CALU – turn CAL mode OFF CAL1 – turn CAL mode ON | |
| ATT | ATT <attenuator><level></level></attenuator> | Set the digital attenuators. |
| | /// Cattoridator/Novol/ | Sot the digital attenuators. |
| | Where attenuator is 1, 2, 3 or 4 and <level></level> | |
| | must be a 2 digit hex number. Valid values | |
| | for <level> are 0 through 31 corresponding</level> | |
| | to 0dB through 31dB. The upper 3 bits are | |
| | masked and so are therefore no cares. | |
| STD | STD <delay></delay> | Set the scope trigger delay. |
| | | |
| | Where delay is a decimal multiple of 20ns | |
| | and can range from 0 to 255. | |

| STD? | return the scope trigger delay, a number | Return the scope trigger |
|---------------|--|------------------------------|
| OID: | from 0 to 255 | delay. |
| TXMODE | TXMODEd | Set the transmit mode of |
| INVIOUE | TAIVIODEU | the 1090/1030 board. |
| | TXMODE0 – 1090 mode | the 1090/1030 board. |
| | | |
| GPS | TXMODE1 – 1030 mode GPS0 – GPS mode off | If the GPS1 command is |
| GPS | | |
| | GPS1 – GPS mode on | received and odd/even |
| | | second information has not |
| | | been received from the |
| | | Resolution T GPS board a |
| | | question mark will be |
| | | returned and GPS mode |
| | | will not be turned on. In |
| | | GPS mode a scenario is |
| | | started on an even PPS. |
| | | When not in GPS mode a |
| | | scenario is started |
| | | whenever the RUN |
| | | command is received |
| // | Comment Line | Used for inline commenting |
| The following | g 16 commands are for internal use only | |
| FSCR | | Set Freq Synth clock rate in |
| | | KHz |
| FSCR? | | Request Freq Synth clock |
| | | rate in KHz |
| FSBC | | Set Freq Synth bit count |
| FSBC? | | Request Freq Synth bit |
| | | count |
| FSD | | Set Freq Synth data |
| FSD? | | Request Freq Synth data |
| FSR | | Reset the Freq Synth and |
| | | the DDS |
| DDSBC | | Set DDS bit count |
| DDSBC? | | Request DDS bit count |
| DDSCR | | Set DDS clock rate in KHz |
| DDSCR? | | Request DDS clock rate in |
| DDOOK! | | KHz |
| DDSD | | Set DDS data |
| | | |
| DDSD? | | Request DDS data |
| DEST | | Set the destination for the |
| DECTO | | DDS commands |
| DEST? | | Request the destination for |
| 555 | | the DDS commands |
| REST | | Pass command strings on |
| | | to the Resolution T |
| | | GPSbBoard |

1090 NON-WAYPOINT SPECIFIC COMMANDS

| Command | Format | Definition |
|---------|--|--|
| TARG | TARG <int>, 0 to 44</int> | Select the target to define. Only targets 0-9 can have associated waypoints |
| DF= | DF=17 DF=18 DF=19 | Select what type of squitters we are transmitting. |
| DF17 | various (see below) | Set the default DF17 data for the selected target. |
| | | The AA field will be overwritten by the provided mode S address. If no mode S address is provided all zeroes will be used. |
| | | The latitude, longitude and altitude will be overwritten by values as determined while the scenario is running. |
| | | The airborne velocities will be overwritten by values as determined while the scenario is running. |
| | | The CA and SSS fields will be overwritten by values as determined while the scenario is running based on TI and TC timers and the ALERT flag. |
| | | The PI field will be calculated. |
| MSAD | MSADhhhhhh | Set the mode S address for the selected target in hex |
| UNIT | UNIT0 = DMS UNIT1 = floating point | Define the units for the LAT and LONG commands |
| WOW | WOW0 = no weight on wheels WOW1 = weight on wheels | Set the weight on wheels detection capability for the present target |
| СОММ | COMM0 = no COMM1 = yes | Set the COMM A/B capability for the present target |

| \/== | \/FD 0 0 | 0 1 1 1 |
|---------|---|---|
| VER | VERd, 0 to 2 VER0 = DO-260 | Set whether we use DO-260 defined type codes (version |
| | VER1 = DO-260A | 0), DO-260A defined type |
| | VER2 = DO-260B | codes (version 1), or DO- |
| | | 260B defined type codes |
| 1.7/1.0 | 11/401 | (version 2) |
| LVLO | LVLOd | Set the attenuation for the |
| | | present target. Range: 0 to |
| | | 31dBm |
| | 051017 | Resolution: 1dBm |
| CF | CFd, 0 to 7 | Define the CF field for the |
| 001011 | 001011 | selected target |
| CSIGN | CSIGNaaaaaaaaa, where aaaaaaaa is 8 | Define the call sign/flight ID |
| | ascii characters, 0-9, A-Z, or space. If you | for the selected target. |
| | want to set one of the characters to one of | |
| | the other available values use the following: | |
| | \ = 37 (not available) | |
| |] = 38 (reserved) | |
| 1.510 | ^ = 39 (reserved) | |
| LENG | LENGd, 0 to 7 | Define the length code field |
| MID | N/ID L O A | for the selected target. |
| WID | WIDd, 0 or 1 | Define the width code field |
| DO 4 | POAG II I | for the selected target. |
| POA | POA0 = not applied | Define the position offset |
| | POA1 = applied | applied flag for the selected |
| | | target. (Only applies to V1 |
| 10000 | 11/0000 | targets) |
| VVSRC | VVSRC0 = geometric | Define the vertical velocity |
| | VVSRC1 = barometric | source field for the selected |
| | 11700 | target. |
| UTC | UTC0 = not coupled | Define the UTC field for the |
| ENAIT | UTC1 = coupled | selected target. |
| EMIT | EMIT <int>, 0 to 31</int> | Define the emitter category |
| | Set A = EMIT 0 to 7; | for the selected target. |
| | Set B = EMIT 8 to 15; | |
| | Set C = EMIT 16 to 23; | |
| | Set D = EMIT 24 to 31; | |
| BAIC | D7 = EMIT 32+ BAIC0 = Barometric Pressure Altitude has | Define the Barometric |
| DAIC | NOT been cross checked | Altitude Integrity Code for |
| | BAIC1 = Barometric Pressure Altitude has | |
| | been cross checked | the selected target |
| TM | TM0 = referenced to true north | Define the True/Magnetic |
| I IVI | | |
| | TM1 = referenced to magnetic north | Indicator flag for the |
| HT | HTO - heading | Selected target |
| וחו | HT0 = heading HT1 = track | Define the Heading/Track |
| | IIII = liack | Indicator flag for the |
| ECINI | 1000INO – No 1000 Passiva sanahilitri | selected target |
| ESIN | 1090IN0 = No 1090 Receive capability | Define the 1090ES IN field |
| ΛD\/ | 1090IN1 = 1090 Receive capability | for the selected target |
| ARV | ARV0 = No ARV Capability | Define the Air-referenced |
| | ARV1 = ARV Capability | Velocity Report Capability |
| | | field for the selected target |

| | T | T_ |
|--------|---|-------------------------------|
| TS | TS0 = No Target State Report Capability | Define the Target State |
| | TS1 = Target State Report Capability | Report Capability field for |
| | | the selected target |
| TC | TCd, 0 to 3 | Define the Target Change |
| | | Report Capability field for |
| | | the selected target |
| UATIN | UATIN0 = No UAT Receive Capability | Define the UAT IN field for |
| | UATIN1 = No UAT Receive Capability | the selected target |
| B2LOW | B2LOW0 = Greater than or equal to 70W | Define the B2 Low Field for |
| | Tx | the selected target |
| | B2LOW1 = Less than 70W Tx | - |
| SANT | SANT0 = Systems with two functioning | Define the Single Antenna |
| | antennas | Flag Field for the selected |
| | SANT1 = Systems that use only one | target |
| | antenna | |
| SDA | SDAd, 0 to 3 | Define the System Design |
| | | Assurance Field for the |
| | | selected target |
| GPSOFF | GPSOFFd, 0 to 255 | Define the GPS Antenna |
| | | Offset Field for the selected |
| | | target. (Only applies to V2 |
| | | targets) |
| GVA | GVAd, 0 to 3 | Define the GVA for the |
| | | selected target |

1090 WAYPOINT COMMANDS

| Command | Format | Definition |
|---------|--|------------------------------|
| WAYP | WAYP <int>, 0 to 5</int> | Select the waypoint to |
| | | define for the selected |
| | | target. |
| TIME | TIMEd, 0 to 214748364.6 seconds, lsb is | Set the UTC TIME for the |
| | 100ms | present waypoint/target |
| MODS | MODShh, Enable (1) or Disable (0): | Enable/Disable the |
| | bit 0 –DF11 Acq Squitter | squitter types for the |
| | bit 1 –DF17 Ident Squitter | selected target |
| | bit 2 –DF17 Surface Position Squitter | |
| | bit 3 –DF17 Airborne Position Squitter | |
| | bit 4 –DF17 Airborne Velocity Squitter | |
| | bit 5 – Inhibit mode | |
| LAT | if the UNIT0 command was received, the LAT | Set the latitude for the |
| | command will be: | present waypoint/target |
| | | |
| | LAT <deg>,<min>,<sec></sec></min></deg> | |
| | | |
| | | |
| | | |
| | <deg>, degrees, 0 to 90 for North, 0 to -</deg> | |
| | <ueg>, degrees, 0 to 90 for North, 0 to -</ueg> | |
| | 90 for South | |
| | 30 for Codin | |
| | | |
| | <min>, minutes, 0 to 59</min> | |
| | <sec>, seconds, 0 to 59</sec> | |
| | | |
| | if the UNIT1 command was received, the LAT | |
| | command will be: | |
| | LAT <float>, 0.0 to 90.0 for North, 0.0 to -90.0</float> | |
| | for South | |
| LONG | if the UNIT0 command was received, the | Set the longitude for the |
| LONG | LONG command will be: | present waypoint/target |
| | EGIVO GOMMANA WIII DC. | present waypoint target |
| | LONG <deg>,<min>,<sec></sec></min></deg> | |
| | | |
| | <deg>, degrees, 0 to 180 for East, 0 to -180</deg> | |
| | for West | |
| | <min>, minutes, 0 to 59</min> | |
| | <sec>, seconds, 0 to 59</sec> | |
| | | |
| | if the UNIT1 command was received, the | |
| | LONG commands will be: | |
| | | |
| | LONG <float>, 0.0 to 180.0 for East, 0.0 to -</float> | |
| | 180.0 for West | |
| AT | AT0 = pressure | Define the altitude type for |
| | AT1 = geometric | the selected target |

| A . T | ALT 1 4000 (- 400500 f) | Ont the additional after the a |
|-------|---|--------------------------------|
| ALT | ALT <long>, -1000 to 126500 feet</long> | Set the altitude for the |
| ALTD | ALTD4 OF () I i' | present waypoint/target |
| ALTR | ALTR1 = 25 foot resolution | Set the altitude resolution |
| | ALTR0 = 100 foot resolution | for the present |
| | | waypoint/target |
| ICF | ICF0 = No Intent Change | Define the Intent Change |
| | ICF1 = Intent Change | Flag field for the selected |
| | | target |
| GSIGN | GSIGN0 = Above Baro | Define the Difference Sign |
| | GSIGN1 = Below Baro | Bit field for the selected |
| | | target |
| GHD | GHD <int>, -25 to 3150 feet (25' steps)</int> | Define the Geometric |
| | (where -25 represents an ALL ZEROs | Height Difference from |
| | encoding) | Baro Alt. field for the |
| | | selected target |
| VS | VS0 = in the air | Set the vertical status for |
| | VS1 = on the ground | the present |
| | y o y o y o y o y o y | waypoint/target |
| TRK | TRK <int>, 0 to 360 degrees</int> | Define the track angle for |
| | , o to ooo dogrood | the selected target |
| HDG | HDG <float>, 0 to 360 degrees</float> | Set the Heading/Ground |
| 1120 | Resolution = 360/128 degrees | Track field in the surface |
| | 17C30Idilo11 = 300/120 degices | message |
| HDGS | HDGS0 = heading invalid | Set the status for |
| проз | | |
| MOV | HDGS1 = heading valid | Heading/Ground Track |
| MOV | MOV0 = stopped | Set the on-the-ground |
| | MOV1 = moving | moving status for the |
| 0000 | 000011 | present waypoint/target |
| GSPD | GPSDd <float></float> | Set the ground speed |
| | | (kts) for the present |
| | | waypoint/target |
| NACP | NACPh, 0x0 to 0xf | Define NACP field for the |
| | | selected target. |
| NACV | NACV d, 0 to 7 | Define NACV field for the |
| | | selected target. |
| NIC | NIC.h, 0 to f | Define the NIC field for |
| | | the selected target |
| | note: the . between the command and the | |
| | data is necessary when the command is less | |
| | than four characters and the data is alpha i.e. | |
| | the characters a-f in hex numbers. | |
| NICA | NICA0 = Set NIC Supplement A to 0 | Define the NIC |
| | NICA1 = Set NIC Supplement A to 1 | Supplement A field for the |
| | | selected target |
| NICB | NICB0 = Set NIC Supplement B to 0 | Define the NIC |
| 55 | NICB1 = Set NIC Supplement B to 1 | Supplement B field for the |
| | | selected target |
| NICC | NICC0 = Set NIC Supplement C to 0 | Define the NIC |
| INICO | NICC1 = Set NIC Supplement C to 0 | Supplement C field for the |
| | INICOT = Set INIC Supplement C to 1 | 1 |
| MODA | MODAd suboro dio the decaded Made O/A | selected target |
| MODA | MODAd, where d is the decoded Mode 3/A | Define the Mode 3/A code |
| | code in octal representation (i.e. 1200) | for the selected target. |
| | | |

| EPS | EPSd, 0 to 7 | Define the Emergency Priority Status field for the selected target. |
|---------|--|--|
| SIL | SILd, 0 to 3 | Define Surveillance Integrity Level field for the selected target. |
| SSUP | SSUP0 = Prob of exceeding NIC on "per hour" SSUP1 = Prob of exceeding NIC on "per sample" | Define SIL Supplement field for the selected target. |
| TCAS | TCAS0 = Not Operational TCAS1 = Operational | Define the TCAS Operational field for the selected target |
| RA | RA0 = no RA1 = yes | Define the TCAS Resolution Advisory Active flag for the selected target |
| ERRM | various (see below), the error mask will be XORed with the DF17 data prior to transmission | Define the error mask for a specific squitter type for the selected target |
| ERRM11 | ERRM110xhhhhhhhhhhhhhh | Set the DF11 error mask |
| ERRM | ERRM0xhhhhhhhhhhhhhhhhhhhhhhhhhhhhhhhhhhh | Set the DF17 Ident error mask |
| ERRMSPO | ERRMSPOoxhhhhhhhhhhhhhhhhhhhhhhhhhhhhhhhhhhhh | Set the DF17 Surface Position – ODD epoch error mask |
| ERRMSPE | ERRMSPE0xhhhhhhhhhhhhhhhhhhhhhhhhhhhhhhhhhhhh | Set the DF17 Surface Position data – EVEN epoch error mask |
| ERRMAPO | ERRMAPOoxhhhhhhhhhhhhhhhhhhhhhhhhhhhhhhhhhhhh | Set the DF17 Airborne Position – ODD epoch error mask |
| ERRMAPE | ERRMAPE0xhhhhhhhhhhhhhhhhhhhhhhhhhhhhhhhhhhhh | Set the DF17 Airborne Position – EVEN epoch error mask |
| ERRMAV | ERRMAV <mark>0x</mark> hhhhhhhhhhhhhhhhhhhhhhhhhhhhhhhhhhhh | Set the DF17 Airborne Velocity error mask |

Note: The waypoint commands, with the exception of WAYP and TIME are also valid for non-moving targets.

1090 EVENT-POINT COMMANDS

| ETIME | ETIMEd, d = 0 to 214748364.6 seconds, lsb is 100ms | Set an event and its associated Start time for the present target. Events must be defined in sequential order. You may define up to 100 event points total across all of the targets. An event point can have any or all of the event types associated with it. |
|----------|---|---|
| RATE23 | RATE23d where d = d = 0 to 214748364.7 seconds, lsb is 100ms | Set a HTC23 event's interval time for the present target. Transmit randomly within +/- 0.2s of specified interval. |
| RATE28 | RATE28d where d = d = 0 to 214748364.7 seconds, lsb is 100ms | Set a HTC28 event's interval time for the present target. Transmit randomly within +/- 0.2s of specified interval. |
| RATE29 | RATE29d where d = d = 0 to 214748364.7 seconds, lsb is 100ms | Set a HTC29 event's interval time for the present target. Transmit randomly within +/- 0.2s of specified interval. |
| RATE31 | RATE31d where d = d = 0 to 214748364.7 seconds, lsb is 100ms | Set a HTC31 event's interval time for the present target. Transmit randomly within +/- 0.2s of specified interval. |
| IDENT | | Set an IDENT event point for the selected target |
| SQUAWK | | Set a SQUAWK event point for the selected target |
| ALERT | | Set an ALERT event point for the selected target. If you want to turn the ALERT off send an ETIME command followed by no event types |
| LVLO | LVLOd | Set an ATTENuation for the selected target. Range: 0 to 31dBm Resolution: 1dBm |
| DF17TC23 | DF17HTC230xhhhhhhhhhhhhhhhh, the 14 hex digits are bytes 5 through 11 of the reply data with the msb being bit 1 of byte 5. | Set the DF17 Type 23 message for the selected target. |

| DF17TC28 | DF17HTC280xhhhhhhhhhhhhhhhhhhhhhhhhhhhhhhhhhhhh | Set the DF17 Type 28 message for the selected target. The EPS and MODA fields will be overwritten with data from those commands. Set the DF17 Type 29 message for the selected |
|----------|--|--|
| | hex digits are bytes 5 through 11 of the reply data with the msb being bit 1 of byte 5. | target. The NACP, BAIC, SIL, TCAS, SSUP (ver 2), RA (ver 1) and EPS (ver 1) fields will be overwritten with data from those commands. |
| DF17TC31 | DF17HTC310xhhhhhhhhhhhhhhh, the 14 hex digits are bytes 5 through 11 of the reply data with the msb being bit 1 of byte 5. | Set the DF17 Type 31message for the selected target. The POA, ESIN, B2LOW, LENG, WID, RA, D0260VER, NICA, NACP, SIL, HT, TM, ARV, TS, TC, BAIC, SSUP, UATIN, NACV, NICC, SANT, SDA, GPSOFF, TCAS, GVA and SIL fields will be overwritten with data from those commands depending on what version of the mops the target is emulating and vertical status of the target |
| EVSQ | EVSQh, Enable (1) or Disable (0): bit 0, Enable (1) or Disable (0) DF17 type code 23 bit 1, Enable (1) or Disable (0) DF17 type code 28 bit 2, Enable (1) or Disable (0) DF17 type code 29 bit 3, Enable (1) or Disable (0) DF17 type code 31 | Enable/Disable the squitter types for the selected target Note: Any time you use the EVSQ you may want to also send associated DF17TC commands to define the bits in the squitter that are not defined by other commands. |
| EVMS | EVMShh, Enable (1) or Disable (0): bit 0, Enable (1) or Disable (0) DF11 Acquisition Squitter bit 1, Enable (1) or Disable (0) DF17 Ident Squitter bit 2, Enable (1) or Disable (0) DF17 Surface Position Squitter bit 3, Enable (1) or Disable (0) DF17 Airborne Position Squitter bit 4, Enable (1) or Disable (0) DF17 Airborne Velocity Squitter | Enable/Disable the squitter types for the selected target |

1030 COMMANDS

| BRAT | BRAT <float>, 1.0 – 16.0 seconds</float> | Define the burst rate, i.e. the rotation rate of the antenna. Resolution is 0.1 second. |
|------|---|--|
| BLEN | BLEN <float>, 1.0 – 16.0 seconds</float> | Define the burst length, i.e. the "beam width" of the antenna. Resolution is 0.01 second. Must be no bigger than the burst rate. |
| IT | where dd is the interrogation number 01-04 are the beam interrogations 05-50 are the random interrogations type is one of the following: A – ATCRBS mode A | Define the 50 different interrogations that will appear in the antenna beam. |
| | AA – ATCRBS mode A, all call AOA – ATCRBS mode A only, all call C – ATCRBS mode C CA – ATCRBS mode C, all call COA – ATCRBS mode C only, all call Sdd, where the dd selects one of up to 50 different possible mode S definitions | |
| PRF | PRF <int>, 1 to 500 interrogations per second</int> | Define the interrogation rate for the interrogations in the antenna beam |
| SDAT | SDATdd<14 hex characters> or SDATdd<28 hex characters> where dd, 01 to 50, must be two characters | Specify the data for one of the 50 possible mode S interrogations. Provide 14 hex characters to define a short mode S, 28 hex characters to define a long mode S. |
| SMSK | SDATdd<14 hex characters> or SDATdd<28 hex characters> where dd, 01 to 50, must be two characters | Specify the error mask for one of the 50 possible mode S interrogations. Provide 14 hex characters for a short mode S, 28 hex characters for a long mode S. The error mask is XORed with the mode S data so a one bit in the mask introduces an error. |
| STON | STON <slot> where <slot> is 1 to 4</slot></slot> | Turn the scope trigger ON for the specified interrogation slot in the antenna beam. |

| STOFF | STOFF <slot></slot> | Turn the scope trigger OFF |
|-------|---|-----------------------------|
| | | for the specified |
| | where <slot> is 1 to 4</slot> | interrogation slot in the |
| | | antenna beam. |
| LVLO | LVLOdd <offset></offset> | Set the attenuation for the |
| | | present target. |
| | Where dd is the interrogation number | |
| | 01 – 04 are the beam interrogations | |
| | 05-50 are the random interrogations | |
| | <offset> is 0 to 31 dBm with 1 dBm</offset> | |
| | increments | |

UAT SYSTEM COMMANDS

| Command | Format | Definition |
|---------|---|--|
| DLD | | Download the |
| | | microprocessor code |
| PGM | PGM – Programs the FPGA directly from | Download RF Board FPGA code |
| | the downloaded file | |
| | PGM0 – store the downloaded file in the onboard EEPROM for FPGA1 | |
| | PGM1 – Programs the FPGAs with the images contained in the onboard EEPROM | |
| | PGM2 – store the downloaded file in the onboard EEPROM for FPGA2 | |
| RST | | Reset the RF Board to its |
| | TVE (I - OF OF OF OF OF OF OF | power-up state |
| TXF | TXF <float>, 952.00 – 1223.00 MHz</float> | Set the Transmit |
| | | synthesizer frequency |
| BTR? | Return example: | Request the BOOT code |
| | KOR RF Bd Boot Rev: 0.1; Date: 02/24/2006 | revision string. |
| GAR? | Return example: FPGA Rev Number: 65 | Request the FPGA1 revision string |
| RFR? | Return example: | Request the RF board |
| IXI IX: | SQTR Gen Rev: 0.01; Date: 10/12/07 | revision string |
| SBY | , | Pauses the scenario |
| RUN | | Starts the scenario |
| STOP | | Stop the scenario |
| STOP | STOP <long></long> | Set the stop time for the |
| | | scenario. |
| | | LSB is 100ms. |
| | | Setting the stop time to the |
| | | maximum value |
| | | (2147483647) |
| | | essentially makes the |
| | | scenario infinite. |
| | | Range: 0 to 2147483647 |
| | | Resolution: 100ms |
| LVL | LVLd | Set the RF Level. |
| | | Range: 13 to –111dBm Resolution: 1dBm |
| SAVE | | Save the scenario to |
| SAVE | | EEPROM |

| MODE | MODEd | Set the operating mode of the SQTR1. |
|-------|---|---|
| | | 0 = do not initialize with stored scenario, wait for user commands 1 = initialize with the stored scenario, wait for user commands 2 = initialize with the stored scenario, run to stop time 3 = initialize with the stored scenario, run to stop time and repeat |
| RAW? | return example: | Return the average raw temperature reading. |
| TMP? | return example: | Return the computed temperature (using the average raw temperature reading, calibrated slope and calibrated offset). |
| ТМРО | TMPO <float></float> | Set the offset for the temperature sensor transfer function. |
| TMPO? | return example: | Return the offset for the temperature sensor transfer function. |
| TMPS | TMPS <float></float> | Set the slope for the temperature sensor transfer function. |
| TMPS? | return example: | Return the slope for the temperature sensor transfer function. |
| CATT | CATT <coarse attenuation="" cal="" table=""></coarse> | Download the coarse attenuation calibration table. The CATT table is a two dimensional table (RF level vs. attenuator) containing values to be written to the 4 digital attenuators and an index into the FATT tables used to set the pin diode attenuator for each RF level setting from 13 to -111. |

| FATT | FATTd <fine attenuation="" cal="" table=""></fine> | Download the fine |
|------|---|--|
| | | attenuation tables. The |
| | FATT0 – download the FATT table for the | FATT tables are two |
| | UAT frequency of 978 MHz | dimensional tables (index |
| | | from the CATT table vs. |
| | FATT1 - download the FATT table for the | temperature) containing |
| | ground station frequency of 1030 MHz | values to be added to the |
| | | value obtained from the |
| | FATT2 - download the FATT table for the | BATT table and written to |
| | squitter frequency of 1090 MHz | the pin-diode to achieve the |
| | | "tweak" required to achieve |
| | | the requested RF level |
| | | once the four digital |
| | | attenuators are set to get as close to it as possible |
| BATT | BATTd <frequency attenuation="" band="" cal<="" td=""><td>Download the frequency</td></frequency> | Download the frequency |
| | table> | band attenuation tables. |
| | | The BATT tables are two |
| | BATT0 – download the BATT table for the | dimensional tables (index |
| | UAT frequency of 978 MHz | from the CATT table vs. |
| | | frequency offset band) |
| | BATT1 - download the BATT table for the | containing values to be |
| | ground station frequency of 1030 MHz | added to the value obtained |
| | | from the FATT table and |
| | BATT2 - download the BATT table for the | written to the pin-diode to |
| | squitter frequency of 1090 MHz | achieve the "tweak" |
| | | required to achieve the |
| | | requested RF level once |
| | | the four digital attenuators are set to get as close to it |
| | | as possible |
| CW | CW <channel><on off=""></on></channel> | Turn CW mode on or off on |
| | | each of the three channels. |
| | CW10 – turn CW OFF on channel 1 | |
| | CW11 – turn CW ON on channel 1 | |
| | CW20 – turn CW OFF on channel 1 | |
| | CW21 – turn CW ON on channel 1 | |
| | CW30 – turn CW OFF on channel 1 | |
| 0.41 | CW31 – turn CW ON on channel 1 | Turn CAL |
| CAL | CAL <on off=""></on> | Turn CAL mode off and on. |
| | CAL0 – turn CAL mode OFF | |
| | CAL1 – turn CAL mode OFF | |
| ATT | ATT <attenuator><level></level></attenuator> | Set the digital attenuators. |
| | 711 Aditionator Storole | Cot the digital attendators. |
| | Where attenuator is 1, 2, 3 or 4 and <level></level> | |
| | must be a 2 digit hex number. Valid values | |
| | for <level> are 0 through 31 corresponding</level> | |
| | to 0dB through 31dB. The upper 3 bits are | |
| | masked and so are therefore no cares. | |
| STD | STD <delay></delay> | Set the scope trigger delay. |
| | | |
| | Where delay is a decimal multiple of 20ns | |
| | and can range from 0 to 255. | |

| STD? | return example: | Return the scope trigger |
|--------|---|-----------------------------|
| | Totalii oxampio. | delay. |
| GPS | GPS0 – simulate PPS | Select the source for the |
| | GPS1 – use PPS from Resolution T GPS | PPS. This allows you to |
| | board | simulate the PPS if you are |
| | | not receiving one from the |
| | | GPS board. The default |
| | | setting is to use the PPS |
| | | from the GPS board. |
| // | Comment Line | Used for inline commenting |
| | g 16 commands are for internal use only | |
| FSCR? | | Request Freq Synth clock |
| | | rate in KHz |
| FSBC | | Set Freq Synth bit count |
| FSBC? | | Request Freq Synth bit |
| | | count |
| FSD | | Set Freq Synth data |
| FSD? | | Request Freq Synth data |
| FSR | | Reset the Freq Synth and |
| | | the DDS |
| DDSBC | | Set DDS bit count |
| DDSBC? | | Request DDS bit count |
| DDSCR | | Set DDS clock rate in KHz |
| DDSCR? | | Request DDS clock rate in |
| | | KHz |
| DDSD | | Set DDS data |
| DDSD? | | Request DDS data |
| DEST | | Set the destination for the |
| | | DDS commands |
| DEST? | | Request the destination for |
| | | the DDS commands |
| REST | | Pass command strings on |
| | | to the Resolution T |
| | | GPSbBoard |

UAT NON-WAYPOINT SPECIFIC COMMANDS

| Command | Format | Definition |
|---------|---|--|
| TARG | TARG <int>, 0 to 9</int> | Select the target to |
| | | define. |
| ACT | ACT <int>, 0 to 9</int> | Activates a target |
| DATA | DATA <payl><28 or 60 hex digits></payl> | Set the default data for the specified payload for the selected target. |
| | | Payloads 00 to 06 correspond to payload types 0 to 6. |
| | | (Most of the bits will be overwritten by data for the specific fields.) |
| | | Payloads 07 to 12 are not defined to be certain payload types and can be defined by the user. |
| | | (Since these payloads are not defined to be any specific type they will not be overwritten by data for specific fields.) |
| MSAD | MSADhhhhhh | Set the mode S address for the selected target in hex |
| UNIT | UNIT0 = DMS UNIT1 = floating point | Define the units for the LAT and LONG commands |
| LVLO | LVLOd | Set the attenuation for the present target. |
| | | Range: 0 to 31dBm Resolution: 1dBm |

| EPOCH | EPOCHdd,dd,dd,dd,dd,dd,dd,dd,dd,dd,dd,dd,dd, | Define the payload type for each of the 16 epochs for the present target. |
|--------|---|--|
| | Each of the 16 elements are initialized to 0x20 to indicate undefined. If you want a target to skip an epoch, set that element to 0x20. | |
| AQ | AQd, 0 to 7 | Define the address qualifier field for the selected target |
| AT | ATO = pressure | Define the altitude type |
| LENG | AT1 = geometric LENGd, 0 to 7 | for the selected target Define the length code |
| LLINO | | field for the selected target. |
| WID | WIDd, 0 or 1 | Define the width code field for the selected target. |
| POA | POA0 = not applied POA1 = applied | Define the position offset applied flag for the selected target. (For Version 1 targets only) |
| GPSOFF | GPSOFFd, 0 to 63 | Define the GPS Antenna Offset Field for the selected target. (For Version 2 targets only) |
| VVSRC | VVSRC0 = geometric VVSRC1 = barometric | Define the vertical velocity source field for the selected target. |
| UTC | UTC0 = not coupled UTC1 = coupled | Define the UTC field for the selected target. |
| EMIT | EMIT <int>, 0 to 39</int> | Define the emitter category for the selected target. |
| CSIGN | CSIGNaaaaaaaa, where aaaaaaaa is 8 ascii characters, 0-9, A-Z, or space. If you want to set one of the characters to one of the other available values use the following: \ = 37 (not available)] = 38 (reserved) ^ = 39 (reserved) | Define the call sign (tail number) field for the selected target. |

| FLID | FLIDaaaaaaaa, where aaaaaaaa is 8 ascii | Define the flight plan ID |
|------|---|--|
| | characters, 0-9, A-Z, or space. If you want to set one of the characters to one of the other available values use the following: \ = 37 (not available) | (Mode 3/A) field for the selected target. |
| |] = 38 (reserved) ^ = 39 (reserved) | |
| EPS | EPSd, 0 to 7 | Define the Emergency Priority Status field for the selected target. |
| UMV | UMVd, 0 to 7 | Define UAT MOPS Version Number field for the selected target. |
| SDA | SDAd, 0 to 3 | Define the System Design Assurance Field for the selected target |
| BAIC | BAIC0 = Barometric Pressure Altitude has NOT been cross checked BAIC1 = Barometric Pressure Altitude has been cross checked | Define the Barometric Altitude Integrity Code for the selected target |
| CC1 | CC10 = no CC11 = yes | Define the UAT IN Capability flag for the selected target |
| CC2 | CC20 = no CC21 = yes | Define the 1090 IN Capability flag for the selected target |
| CC3 | CC30 = no CC31 = yes | Define the TCAS/ACAS Installed and Operational flag for the selected target |
| RA | RA0 = no RA1 = yes | Define the Resolution Advisory Active flag for the selected target |
| RAS | RAS0 = no RAS1 = yes | Define the Receiving ATC Services flag for the selected target |
| ТМ | TM0 = referenced to true north TM1 = referenced to magnetic north | Define the True/Magnetic Indicator flag for the selected target |
| CSID | CSIDd, 0 to 2 CSID0 = flight plan ID (Mode 3A) CSID1 = call sign (tail number) CSID2 = Alternate Call Sign/Flight ID between flight plan ID and call sign (every other message) | Define the Call Sign ID flag and Call Sign/Flight Plan ID field contents for the selected target |
| HT | HT0 = heading HT1 = track | Define the Heading/Track Indicator flag for the selected target |
| TSIH | TSIHd, 0 to 3 | Define the Target Source Indicator (Horizontal) for the selected target |

| NAIL I | MILLALO to O | Define the Mede |
|--------|---|----------------------------|
| MIH | MIHd, 0 to 3 | Define the Mode |
| | | Indicator (Horizontal) for |
| | | the selected target |
| TSIV | TSIVd, 0 to 3 | Define the Target |
| | | Source Indicator |
| | | (Vertical) for the |
| | | selected target |
| MIV | MIVd, 0 to 3 | Define the Mode |
| | | Indicator (Vertical) for |
| | | the selected target |
| THDG | THDGd, 0 to 360 degrees | Define the Target |
| | | Heading for the selected |
| | | target |
| TTRK | TTRKd, 0 to 360 degrees | Define the Target Track |
| | | Angle for the selected |
| | | target |
| TALT | TALT <int>, -1000 to 101150 feet</int> | Define the Target |
| | | Altitude for the selected |
| | | target (100 foot |
| | | resolution) |
| TAT | TAT0 = Pressure Altitude ("Flight Level") - | Define Target Altitude |
| | target altitude is above transition level | Type for the selected |
| | TAT1 = Baro-Corrected Altitude ("MSL") - | target |
| | target altitude is below transition level | |
| TAC | TACd, 0 to 3 | Define the Target |
| | , ' | Altitude Capability for |
| | | the selected target |
| SYNC | SYNChhhhhhhhhh, where hhhhhhhhhh | Define the 36 bit |
| | represents the 36 bits of left justified SYNC | synchronization |
| | | sequence if you want |
| | | them to be non- |
| | | standard. If you do not |
| | | send this command the |
| | | synchronization |
| | | sequence will default to |
| | | the defined ADS-B |
| | | |
| | | sequence. |

UAT WAYPOINT COMMANDS

| Command | Format | Definition |
|---------|--|---------------------------|
| WAYP | WAYP <int>, 0 to 5</int> | Select the waypoint to |
| | | define for the selected |
| | | target. |
| TIME | TIMEd, 0 to 214748364 seconds, lsb is 1 s | Set the UTC TIME for |
| | | the present |
| | | waypoint/target |
| LAT | if the UNIT0 command was received, the LAT | Set the latitude for the |
| | command will be: | present waypoint/target |
| | LAT de que emine en en | |
| | LAT <deg>,<min>,<sec></sec></min></deg> | |
| | | |
| | | |
| | | |
| | <deg>, degrees, 0 to 90 for North, 0 to -90</deg> | |
| | | |
| | for South | |
| | | |
| | <min>, minutes, 0 to 59</min> | |
| | <sec>, seconds, 0 to 59</sec> | |
| | 1000, 00001100, 010 00 | |
| | if the UNIT1 command was received, the LAT | |
| | command will be: | |
| | | |
| | LAT <float>, 0.0 to 90.0 for North, 0.0 to -90.0</float> | |
| | for South | |
| LONG | if the UNIT0 command was received, the | Set the longitude for the |
| | LONG command will be: | present waypoint/target |
| | LONG day min | |
| | LONG <deg>,<min>,<sec></sec></min></deg> | |
| | <deg>, degrees, 0 to 180 for East, 0 to -180 for</deg> | |
| | West | |
| | <min>, minutes, 0 to 59</min> | |
| | <sec>, seconds, 0 to 59</sec> | |
| | , 555, 555, 555 | |
| | if the UNIT1 command was received, the | |
| | LONG commands will be: | |
| | | |
| | LONG <float>, 0.0 to 180.0 for East, 0.0 to -</float> | |
| | 180.0 for West | |
| ALT | ALT <long>, -1000 to 101338 feet</long> | Set the altitude for the |
| 0.41.7 | 0.11 T. 1 | present waypoint/target |
| SALT | SALT <long>, -1000 to 101338 feet</long> | Set the secondary |
| | | altitude for the present |
| 100 | ACO sinhama subasiis | waypoint/target |
| AG | AG0 = airborne – subsonic | Set the A/G state for the |
| | AG2 = airborne - supersonic | present waypoint/target |
| | AG2 = on the ground | |

| DACT | DACTd, 0 or 1 | Set the squittering state |
|---------|--|---------------------------|
| | 0 – activate squittering (default) | for the present |
| | 1 – deactivate squittering | waypoint/target |
| TAH | TAHd, 0 to 3 | Define the track |
| | | angle/heading type field |
| | | for the selected target |
| TRK | TRK <int>, 0 to 360 degrees</int> | Define the track angle |
| IIXX | TRACINIZ, 0 to 300 degrees | _ |
| 1150 | 1100 1 4 04 000 1 | for the selected target |
| HDG | HDG <int>, 0 to 360 degrees</int> | Define the heading for |
| | | the selected target |
| GSPD | GPSD <int>, 0 to 1022 knots</int> | Define the ground speed |
| | | for the selected target |
| NACP | NACPh, 0x0 to 0xf | Define NACP field for |
| | 1.0.1.11, 6.0.1.6.6.7.1 | the selected target. |
| NACV | NACVd, 0 to 7 | Define NACV field for |
| NACV | NACVU, U IU 7 | |
| 0 | 0 | the selected target. |
| SIL | SILd, 0 to 3 | Define Surveillance |
| | | Integrity Level field for |
| | | the selected target. |
| SSUP | SSUP0 = Prob of exceeding NIC on "per hour" | Define SIL Supplement |
| | SSUP1 = Prob of exceeding NIC on "per | field for the selected |
| | sample" | target. |
| NIC | NIC.h, 0 to f | Define the NIC field for |
| INIC | NIC.II, U to I | |
| | water than between the common day of the date | the selected target |
| | note: the . between the command and the data | |
| | is necessary when the command is less than | |
| | four characters and the data is alpha i.e. the | |
| | characters a-f in hex numbers. | |
| GVA | GVAd, 0 to 3 | Define the GVA for the |
| | | selected target |
| SANT | SANT0 = Systems with two functioning | Define the Single |
| 0, 1111 | antennas | Antenna Flag Field for |
| | | • |
| 0.4.7 | SANT1 = Systems that use only one antenna | the selected target |
| SAT | SAT0 = MCP/FCU | Define the Selected |
| | SAT1 = FMS | Altitude Type field for |
| | | the selected target. |
| SA | SA <int>, -32 to 65472 feet</int> | Define the Selected |
| | | Altitude for the selected |
| | | target (32 foot |
| | | resolution) |
| BPS | BPSd, 0 to 511 | Define the Barometric |
| DI 3 | DI 30, 0 to 311 | Pressure Setting for the |
| | | _ |
| | 07170 0 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 | selected target. |
| STAT | STAT0 = Status of Selected Heading fields | Define the Status of |
| | invalid | Selected Heading Fields |
| | STAT1 = Status of Selected Heading fields | for the selected target |
| | valid | |
| SHDG | SHDGd, 0 to 360 degrees | Define the Selected |
| | 2.72 2.4, 2.12 222 409.000 | Heading and Sign for |
| | | • |
| CT | CTO Chatter of MOD/FOLL field for a field | the selected target |
| ST | ST0 = Status of MCP/FCU field invalid | Define the Status of |
| | ST1 = Status of MCP/FCU field valid | MCP/FCU Mode Bits for |
| | | the selected target |
| | | |

| | LABO A CHANGE I | D (; // ADA4 / |
|------|---|---------------------------|
| AP | AP0 = Autopilot Not Engaged | Define the AP Mode |
| | AP1 = Autopilot Engaged | Indicator field for the |
| | | selected target |
| VNAV | VNAV0 = VNAV Not Engaged | Define the VNAV Mode |
| | VNAV1 = VNAV Engaged | Indicator field for the |
| | | selected target |
| MALT | MALT0 = Altitude Hold Mode Not Engaged | Define the ALT Mode |
| | MALT1 = Altitude Hold Mode Engaged | Indicator field for the |
| | | selected target |
| APP | APP0 = Approach Mode Not Engaged | Define the APP Mode |
| | APP1 = Approach Mode Engaged | Indicator field for the |
| | 77 | selected target |
| UPFB | UPFBd, 0 to 7 | Define Uplink Feedback |
| | | field for the selected |
| | | target |
| NICS | NICS0 = NIC Rc is default value | Define NIC Supplement |
| 100 | NICS1 = NIC Rc is 0.3 NM | field for the selected |
| | 111001 = 1110 110 10 0.0 1111 | target |
| BITM | BITMdd hhhhhhhh | Define the bitmask for a |
| 2 | | specific payload type for |
| | Where dd selects which payload the bit mask | the selected target. This |
| | applies to, 0 to 12 (must be two digits) | bit mask is XOR'd with |
| | applies to, o to 12 (must be two digits) | the Payload of the |
| | Where hhhh is the 36 (payload 0) or 68 | outgoing message |
| | (payloads 1 to 12) hex digits of the ADS-B | BEFORE |
| | Message Payload | Reed/Solomon Parity |
| | Wessage Fayload | calculations. |
| ERRM | ERRMddhhhhhhhh | Define the error mask |
| | | for a specific payload |
| | where dd selects which payload the error mask | type for the selected |
| | applies to, 0 to 12 (must be two digits) | target. This bit mask is |
| | applies to, o to 12 (must be two digits) | XOR'd with the Payload |
| | where hhhh is the 69 (payload 0) or 105 | of the outgoing message |
| | · · · · · · · · · · · · · · · · · · · | AFTER Reed/Solomon |
| | (payloads 1 to 12) hex digits | |
| | | Parity calculations. |

UAT EVENT-POINT COMMANDS

| ETIME | ETIMEd, d = 0 to 2147483647 seconds | Set an event and its associated Start time for the present target. Events must be defined in sequential order. You may define up to 100 event points total across all of the targets. An event point can have any or all of the event types associated with it. |
|--------|--|---|
| IDENT | | Set an IDENT event point for the selected target |
| SQUAWK | | Set a SQUAWK event point for the selected target |
| ALERT | | Set an ALERT event point for the selected target. If you want to turn the ALERT off send an ETIME command followed by no event types |
| LVLO | LVLOd | Set an ATTENuation for the selected target. Range: 0 to 31dBm Resolution: 1dBm |
| ERRME | ERRMddhhhhhhh where dd selects which payload the error mask applies to, 0 to 12 (must be two digits) where hhhh is the 69 (payload 0) or 105 (payloads 1 to 12) hex digits | Define the error mask for a specific payload type for the selected target to be applied at this eventpoint. This bit mask is XOR'd with the Payload of the outgoing message AFTER Reed/Solomon Parity calculations. |
| EVDA | EVDA1 = deactivate EVDA0 = activate | Activate/Deactivate the selected target at this eventpoint |